

# Addressing Model Ambiguity in the Expected Utility Framework

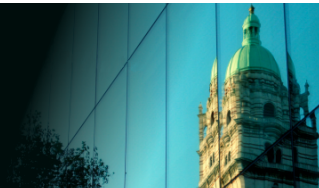
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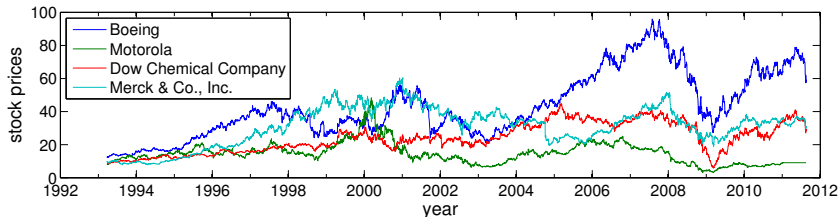
Joint work with Yinyu Ye (Stanford) and Benjamin Armbruster (Northwestern)

**17th British-French-German  
Conference on Optimization**

Monday, June 15th, 2015  
London, United Kingdom



# The Portfolio Selection Problem



- An individual meets with his financial advisor to tell him he wishes to invest in a given industrial sector, country, etc.
- Since uncertain factors affect performance, a “good” portfolio is one where the risks of losses are best justified by the potential gains
- How can one trade-off optimally the risks and the returns taking into account his own perception of what is a serious risk?

# Von Neumann-Morgenstern Expected Utility

If the investor agrees with the following axioms:

- ① Completeness : He can order any two gambles
- ② Transitivity :  $\mathcal{H}_1 \succeq \mathcal{H}_2 \succeq \mathcal{H}_3 \Rightarrow \mathcal{H}_1 \succeq \mathcal{H}_3$
- ③ Continuity : If  $\mathcal{H}_1 \succeq \mathcal{H}_2 \succeq \mathcal{H}_3$  then there is a  $p$  such that  $\mathcal{H}_2 \sim p\mathcal{H}_1 + (1-p)\mathcal{H}_3$
- ④ Independence : If  $\mathcal{H}_1 \succeq \mathcal{H}_2$  then  $p\mathcal{H}_1 + (1-p)\mathcal{H}_3 \succeq p\mathcal{H}_2 + (1-p)\mathcal{H}_3$  for all  $p$  and  $\mathcal{H}_3$

then the preference he expresses between any two gambles must be representable by an expected utility measure:

$$\mathcal{H}_1 \succeq \mathcal{H}_2 \Leftrightarrow E[u(\mathcal{H}_1)] \geq E[u(\mathcal{H}_2)]$$

# Expected Utility Framework

When applying the expected utility framework to a decision problem:

$$\underset{\mathbf{x} \in \mathcal{X}}{\text{maximize}} \quad \mathbb{E} [u(h(\mathbf{x}, \xi))] ,$$

where  $\mathbf{x}$  = decisions,  $\xi$  = uncertain parameters,  $h(\mathbf{x}, \xi)$  = profit,

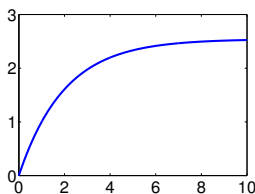
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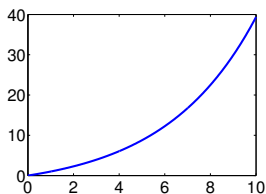
$$\underset{\mathbf{x} \in \mathcal{X}}{\text{maximize}} \quad \mathbb{E}[u(h(\mathbf{x}, \xi))],$$

where  $\mathbf{x}$  = decisions,  $\xi$  = uncertain parameters,  $h(\mathbf{x}, \xi)$  = profit, it is assumed that we know:

- The distribution of the random vector  $\xi$
- A utility function that matches investor's attitude to risk



Retirement Fund



Casino de Monte-Carlo

# Difficulties encountered in practice

Difficulties of developing an accurate probabilistic model:

- Need to collect enough observations
- Need to consult with experts of the field of practice
- Need to make simplifying assumptions
- Unforeseen events (e.g., economic crisis) might occur

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Difficulties of developing an accurate utility function:

- Need to compare a large number of gambles
- Need to accept structural properties
- Perception might be biased

# Modern Robust Optimization Framework

Generally attributed to Ben-Tal & Nemirovski (1998), this framework implements a worst-case approach to dealing with model ambiguity.

$$\max_{\mathbf{x} \in \mathcal{X}} \{h(\mathbf{x}, \mathbf{y})\}_{\mathbf{y} \in \mathcal{Y}} \rightarrow \max_{\mathbf{x} \in \mathcal{X}} \inf_{\mathbf{y} \in \mathcal{Y}} h(\mathbf{x}, \mathbf{y})$$



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Success of the robust optimization relies in part on applying duality to combine inner and outer problems

$$\begin{aligned} \max_{\mathbf{x} \in \mathcal{X}} \min_{\mathbf{y}: \mathbf{A}\mathbf{y} \leq \mathbf{b}} \mathbf{y}^T \mathbf{x} &\equiv \max_{\mathbf{x} \in \mathcal{X}} \min_{\mathbf{y}} \max_{\lambda \geq 0} \mathbf{y}^T \mathbf{x} + \lambda^T (\mathbf{A}\mathbf{y} - \mathbf{b}) \\ &\equiv \max_{\mathbf{x} \in \mathcal{X}} \max_{\lambda \geq 0} \min_{\mathbf{y}} \mathbf{y}^T \mathbf{x} + \lambda^T (\mathbf{A}\mathbf{y} - \mathbf{b}) \\ &\equiv \max_{\mathbf{x} \in \mathcal{X}, \lambda \geq 0} -\mathbf{b}^T \lambda \quad \text{s.t.} \quad \mathbf{x} + \mathbf{A}^T \lambda = 0 \end{aligned}$$

# Robust Expected Utility

In this talk, we investigate how to address model ambiguity in the expected utility framework using robust optimization

- Distributionally robust optimization

$$\underset{\mathbf{x} \in \mathcal{X}}{\text{maximize}} \quad \inf_{F \in \mathcal{D}} \mathbb{E}_F[u(\mathbf{h}(\mathbf{x}, \xi))]$$

- Preference robust optimization

$$\underset{\mathbf{x} \in \mathcal{X}}{\text{maximize}} \quad \text{“} \inf_{u \in \mathcal{U}} \mathbb{E}_F[u(\mathbf{h}(\mathbf{x}, \xi))] \text{”}$$

# Outline

- 1 Introduction
- 2 Distributionally Robust Optimization
- 3 Preference Robust Optimization
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Consider an urn with 30 blue balls and 60 other balls that are either red or green (you don't know how many are red or green).

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Experiment 2: Choose among the following two gambles

- Gamble C: If you draw blue or green ball, then you win 100\$
- Gamble D: If you draw red or green ball, then you win 100\$

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Consider an urn with 30 **blue** balls and 60 other balls that are either **red** or **green** (you don't know how many are **red** or **green**).

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- Gamble A: If you draw a **blue** ball, then you win 100\$
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**Experiment 2:** Choose among the following two gambles

- Gamble C: If you draw **blue** or **green** ball, then you win 100\$
- Gamble D: If you draw **red** or **green** ball, then you win 100\$

If you clearly prefer Gamble A & D, then you are averse to model ambiguity



# Distributionally Robust Optimization

- Let's consider that the choice of  $F$  is ambiguous
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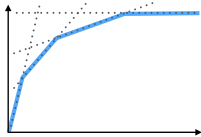
$$(DRO) \quad \underset{\mathbf{x} \in \mathcal{X}}{\text{maximize}} \quad \inf_{F \in \mathcal{D}} \mathbb{E}_F[u(h(\mathbf{x}, \xi))]$$

- Important milestones:
  - 1958: H. Scarf introduces DRO
  - 1989: I. Gilboa et al. introduces maxmin expected utility
  - 2007: I. Popescu solves  $\mu$ - $\Sigma$  portfolio prob.
  - 2010: Bertsimas et al. solves linear  $\mu$ - $\Sigma$  prob.
  - 2010: Goh et al. develops library for Matlab
  - 2010: Delage et al. solves concave-convex  $\mathcal{S}$ - $\tilde{\mu}$ - $\tilde{\Sigma}_{\max}$  prob.
  - 2014: Wiesemann et al. solves or approximates conic prob.

# A Classic Reduction I

Let's make three assumptions about  $\mathbb{E}[u(h(\mathbf{x}, \xi))]$ .

- ① The profit function is concave in  $\mathbf{x}$  and convex in  $\xi$ 
  - In portfolio optimization,  $h(\mathbf{x}, \xi) = \xi^T \mathbf{x}$
- ② The utility function is piecewise linear concave :



$$u(y) = \min_{1 \leq k \leq K} a_k y + b_k$$

- ③ The information about  $F$  is captured by

$$\mathcal{D}(\gamma) = \left\{ F \left| \begin{array}{l} \mathbb{P}(\xi \in \mathcal{S}) = 1 \\ \|\mathbb{E}[\xi] - \hat{\mu}\|_{\hat{\Sigma}^{-1/2}}^2 \leq \gamma_1 \\ \mathbb{E}[(\xi - \hat{\mu})(\xi - \hat{\mu})^T] \preceq (1 + \gamma_2)\hat{\Sigma} \end{array} \right. \right\}$$

## A Classic Reduction II

- The DRO problem with  $\mathcal{D}(\gamma)$  is equivalent to

$$\begin{aligned}
 \max_{\mathbf{x} \in \mathcal{X}} \quad & \inf_F \quad \mathbb{E}_F[u(h(\mathbf{x}, \boldsymbol{\xi}))] \\
 \text{s.t.} \quad & \mathbb{P}_F(\boldsymbol{\xi} \in \mathcal{S}) = 1 \\
 & \|\mathbb{E}_F[\boldsymbol{\xi}] - \hat{\boldsymbol{\mu}}\|_{\hat{\boldsymbol{\Sigma}}^{-1/2}}^2 \leq \gamma_1 \\
 & \mathbb{E}_F[(\boldsymbol{\xi} - \hat{\boldsymbol{\mu}})(\boldsymbol{\xi} - \hat{\boldsymbol{\mu}})^\top] \preceq (1 + \gamma_2)\hat{\boldsymbol{\Sigma}}
 \end{aligned}$$

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## A Classic Reduction II

- The DRO problem with  $\mathcal{D}(\gamma)$  is equivalent to

$$\begin{aligned}
 \max_{\mathbf{x} \in \mathcal{X}} \quad & \max_{\mathbf{Q}, \mathbf{q}, r} \quad r - \left( \gamma_2 \hat{\Sigma} + \hat{\mu} \hat{\mu}^T \right) \bullet \mathbf{Q} - \hat{\mu}^T \mathbf{q} - \sqrt{\gamma_1} \left\| \hat{\Sigma}^{1/2} (\mathbf{q} + 2\mathbf{Q} \hat{\mu}) \right\| \\
 \text{s.t.} \quad & r \leq u(h(\mathbf{x}, \xi)) + \xi^T \mathbf{q} + \xi^T \mathbf{Q} \xi \quad \forall \xi \in \mathcal{S} \\
 & \mathbf{Q} \succeq 0
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 \text{s.t.} \quad & r \leq a_k(h(\mathbf{x}, \xi)) + b_k + \xi^\top \mathbf{q} + \xi^\top \mathbf{Q} \xi \quad \forall \xi \in \mathcal{S}, \forall k \quad (*) \\
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 & \mathbf{Q} \succeq 0
 \end{aligned}$$

- For portfolio selection, if  $\mathcal{S} = \text{polyhedron or ellipsoid}$ , then DRO equivalent to semi-definite program.  
E.g., when  $\mathcal{S} = \mathbb{R}^m$ , constraint  $(\star)$  can be replaced by

$$\begin{bmatrix} \mathbf{Q} & (\mathbf{q} + a_k \mathbf{x})/2 \\ (\mathbf{q} + a_k \mathbf{x})^\top/2 & b_k - r \end{bmatrix} \succeq 0, \quad \forall k$$



# Distributionally Robust Portfolio Optimization

Let's consider the case of portfolio optimization:

$$\max_{\mathbf{x} \in \mathcal{X}} \min_{F \in \mathcal{D}} \mathbb{E}_F[u(\boldsymbol{\xi}^\top \mathbf{x})] \ ,$$

where  $x_i$  is how much is invested in stock  $i$  with future return  $\xi_i$ .

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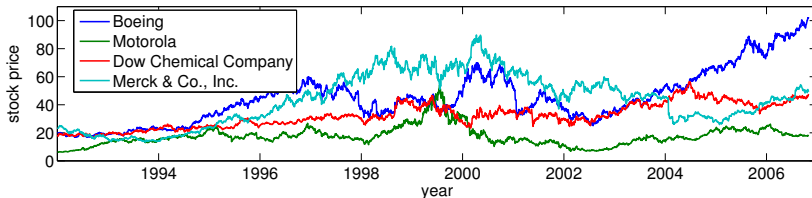
where  $x_i$  is how much is invested in stock  $i$  with future return  $\xi_i$ .

Does the robust solution perform better than solution of expected utility problem with fixed  $\hat{F}$ ?

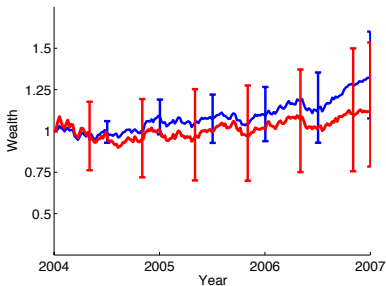
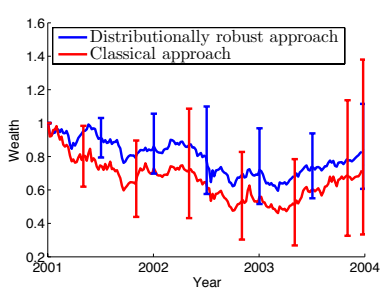
$$\mathcal{D} = \mathcal{D}(\gamma) \quad \text{vs.} \quad \mathcal{D} = \{\hat{F}\}$$

# Experiments in Portfolio Optimization

30 stocks tracked over years 1992-2007 using Yahoo! Finance

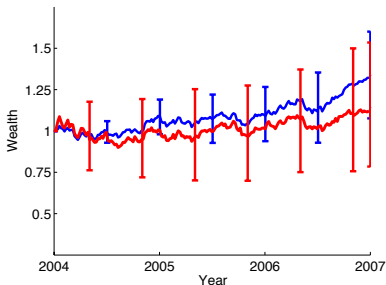
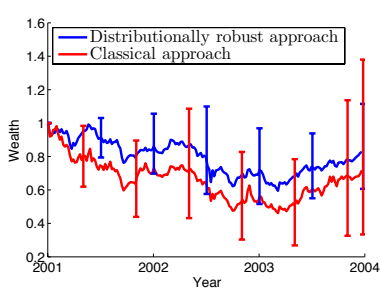


## Wealth Evolution for 300 Experiments



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- 79% of time, the DRO outperformed the classical approach
- 67% improvement on average using DRO with  $\mathcal{D}(\gamma)$

# Other applications

- Territory partitioning for multi-vehicle routing problem with J. G. Carlsson [▶ Details](#)
- Fleet mix optimization problem with S. Arroyo and Y. Ye [▶ Details](#)
- Quadratic knapsack problem with J. Cheng and A. Lisser
- Multi-item newsvendor problem with A. Ardestani-Jaafari
- Many others in scheduling, environmental policies, smart grid management, etc.

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- You have just finished saving for a “once-in-a-lifetime” vacation. Three weeks before you plan to leave, you lose your job. You would:
  - ① Cancel the vacation
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- You are on a TV game show and can choose one of the following. Which would you take?
  - ① \$1,000 in cash
  - ② A 50% chance at winning \$ 5000
  - ③ A 25% chance at winning \$ 10,000
  - ④ A 5% chance at winning \$100,000

# Common Utility Function Estimation Techniques I

Parametric approach:

- One assumes that the function has a specific parametric form
  - Negative exponential utility (CARA)
  - Power utility (CRRA)
  - HARA (incr/decreasing absolute/relative risk aversion)

$$u(y) = \frac{1 - \eta}{\eta} \left( \frac{ay}{1 - \eta} + b \right)^\eta$$

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- Ask enough questions to identify the parameters
- Why it might fail ?
  - Investor must commit to global structure
  - Ignores how confident we are in the final choice of parameters

# Common Utility Function Estimation Techniques II

Non-parametric approach:

- Identify the certainty equivalents of a list of lotteries. By answering:
  - What is the smallest amount  $c_i$  of money you would take instead of playing a lottery  $\mathcal{L}_i$  ?
- Find a piecewise linear utility function that satisfies these certainty equivalents

$$E[u(\mathcal{L}_i)] = u(c_i) \quad \forall i$$

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- Why it might fail ?
  - Expresses risk neutrality between breakpoints
  - Ignores how confident we are in the final choice of  $u(\cdot)$

# Applying the Robust Optimization Framework

Information can be used to characterize a set  $\mathcal{U}$  of plausible utility functions. I.e., any  $u(\cdot)$  such that:

- Global info:
  - Risk aversion :  $u(\cdot)$  is concave
  - Prudence :  $u'(\cdot)$  is convex
  - S-shaped :  $u(\cdot)$  convex-concave
- Local info :

$$E[u(\mathcal{W}_k)] \geq E[u(\mathcal{Y}_k)] \quad \forall k$$

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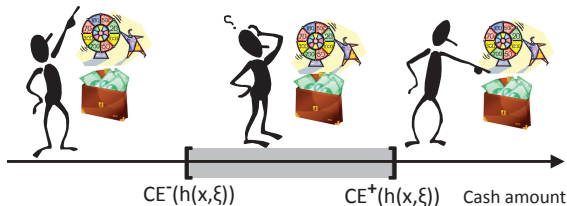
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Even if we force  $u(0) = 0$   $u(1) = 1$ , model promotes risk neutrality.

# Ambiguity about the Certainty Equivalent

- Given a decision  $\mathbf{x}$ , we can start by defining an interval  $[CE^-(h(\mathbf{x}, \xi)), CE^+(h(\mathbf{x}, \xi))]$  of plausible minimum certain return that decision maker would prefer to random profit  $h(\mathbf{x}, \xi)$



# Robust Certainty Equivalent Approach

## Theorem

*Identifying the decision that maximizes the lowest perceived CE*

$$\max_{\mathbf{x} \in \mathcal{X}} CE^{-}(h(\mathbf{x}, \xi)), \text{ a.k.a. } \max_{\mathbf{x} \in \mathcal{X}} \inf_{u \in \mathcal{U}} CE_u(h(\mathbf{x}, \xi)),$$

*can be done efficiently.*

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Proof:

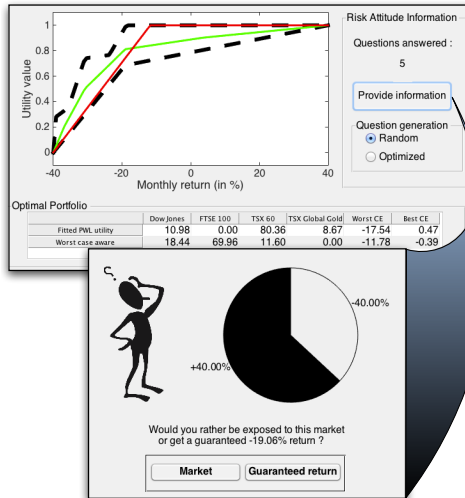
- Objective is quasiconcave and reduces to

$$\max_{\mathbf{x}, t} \quad t \quad \text{s.t.} \quad CE_u(h(\mathbf{x}, \xi)) \geq t \quad \forall u \in \mathcal{U}$$

$$\text{or equiv. } \max_t \quad t \quad \text{s.t.} \quad \max_{\mathbf{x} \in \mathcal{X}} \inf_{u \in \mathcal{U}} E[u(h(\mathbf{x}, \xi))] - u(t) \geq 0$$

- Infimum over  $u \in \mathcal{U}$  can be reduced to finite dimensional program so that duality can be applied [► details](#)

# A Tool for Interacting with Investors



# Numerical experiments

- Obtained from Yahoo! Finance historical stock returns for 350 companies from 1993 to 2011
- Ran extensive amount of trials using last 50 weekly returns to decide investment among 10 assets for next week
- In each experiment, the investor has an unknown risk averse utility function and compares up to 80 pairs of gambles

# Experimental Results

Function optimized	Portfolio's true CE value (in perc. point)		
	5 questions	20 questions	80 questions
Exponential	-0.05	-0.12	<b>-0.13</b>
Fitted PWL	<b>-0.60</b>	-0.11	0.05
Worst-case	-0.14	-0.08	0.06
Worst-case prudent	-0.13	-0.05	0.08
True $\ll \frac{-u''(y)y}{u'(y)} = \frac{20}{y} \gg$	0.12	0.12	0.12

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Observations:

- Using wrong utility function can mislead the choice of portfolio
- Robust approach makes good use of available preference info
- Quality of portfolio is improved as more information is provided



# Accounting for elicitation errors

- Since “to err is human”, we should account for mislabelling of the compared lotteries
- Hence, that for some rand perception noise  $\epsilon$ , we have that

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$$E[u(W_k)] + \epsilon_k \geq E[u(Y_k)]$$

- In that case, one could consider  $u(\cdot)$  plausible as long as  $\exists \delta \geq 0$  such that  $\sum_k \delta_k \leq \Gamma$  and that

$$E[u(W_k)] + \delta_k \geq E[u(Y_k)] \quad \forall k$$

- This can easily be incorporated to the model

# Outline

- 1 Introduction
- 2 Distributionally Robust Optimization
- 3 Preference Robust Optimization
- 4 Conclusion**

# Conclusion & Future Work

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# Conclusion & Future Work

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- Accounting for distribution ambiguity or ambiguity in risk preferences isn't computationally demanding
  - It remains to further study whether both ambiguities can be accounted for jointly (see Haskell et al. 2014)
- Studying the sensitivity of optimal solution with respect to modelled ambiguity can be helpful
  - Value of stochastic modelling
  - Guidance for risk tolerance assessment

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# Questions & Comments ...

... Thank you!

## Dealing with model ambiguity: Ellsberg Paradox

Consider an urn with 30 blue balls and 60 other balls that are either red or green (you don't know how many are red or green).

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Experiment 1: Choose among the following two gambles

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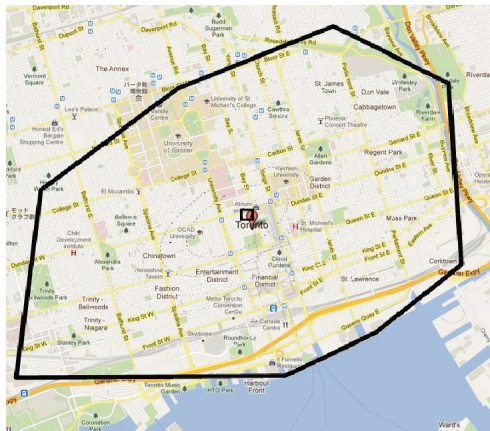
If you clearly prefer Gamble A & D, then you are averse to model ambiguity

# Outline

- 5 Distributionally Robust Partitioning
- 6 Value of Stochastic Modelling in Fleet Composition
- 7 Robust Certainty Equivalent

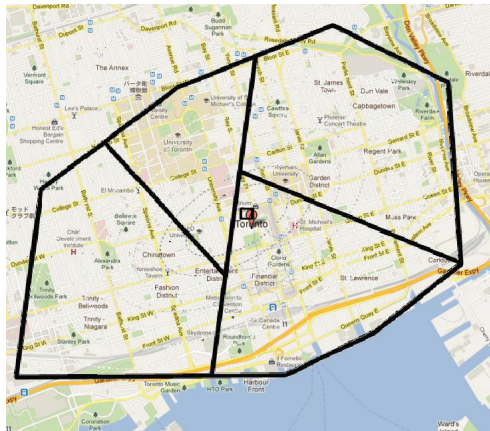
# Multi-Vehicle Routing on a Planar Region

- Divide a planar region into  $K$  subregions, each serviced by a different vehicle, so that the total workload be most evenly distributed among the fleet



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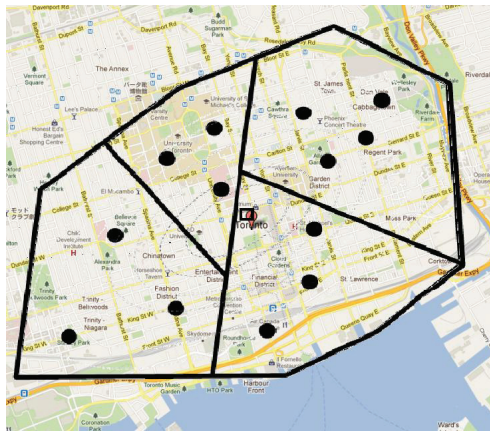
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# Distributionally Robust Partitioning

- Given  $\mathcal{D}$ , we partition so that the largest workload over the worst distribution of demand points is as small as possible

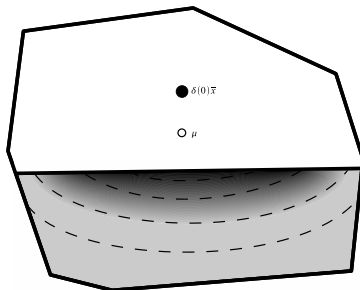
$$\min_{\{\mathcal{R}_1, \mathcal{R}_2, \dots, \mathcal{R}_K\}} \sup_{F \in \mathcal{D}} \left\{ \max_i \mathbb{E}[TSP(\{\xi_1, \xi_2, \dots, \xi_N\} \cap \mathcal{R}_i)] \right\} ,$$

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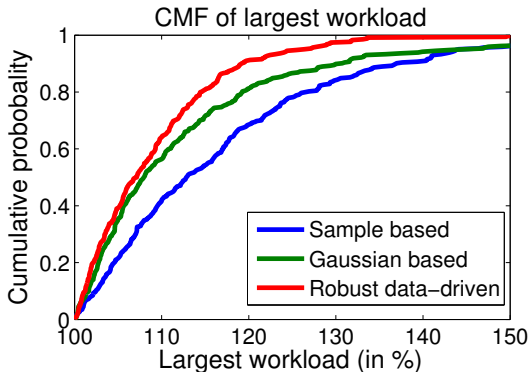
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- A side product is to characterize for any partition what is a worst-case distribution of demand locations



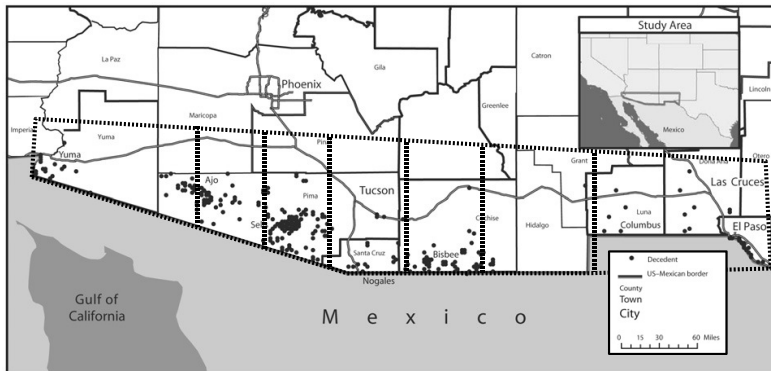
# Distributionally Robust Partitioning

We simulated three partition schemes on a set of randomly generated parcel delivery problems where the territory needed to be divided into two regions and the demand is drawn from a mixture of truncated Gaussian distribution



# Border Patrol Workload Partitioning

Robust partitions of the USA-Mexico border obtained using our branch & bound algorithm.



# Outline

- 5 Distributionally Robust Partitioning
- 6 Value of Stochastic Modelling in Fleet Composition**
- 7 Robust Certainty Equivalent

# The Robustness of the Deterministic Solution

If we are risk neutral we might not even need distribution information

## Theorem

*The solution of*

$$\underset{\mathbf{x} \in \mathcal{X}}{\text{maximize}} \quad \mathbb{E}[h(\mathbf{x}, \mu)]$$

*is optimal with respect to*

$$\underset{\mathbf{x} \in \mathcal{X}}{\text{maximize}} \quad \inf_{F \in \mathcal{D}(\mu, \Psi)} \mathbb{E}_F[h(\mathbf{x}, \xi)] ,$$

*for any set of convex functions  $\Psi$  with*

$$\mathcal{D}(\mu, \Psi) = \left\{ F \mid \begin{array}{l} \mathbb{E}[\xi] = \mu \\ \mathbb{E}[\psi(\xi)] \leq 0, \forall \psi \in \Psi \end{array} \right\} .$$



# The Value of Stochastic Modelling

Consider the situation:

- ① We know of a set  $\mathcal{D}$  such that  $F \in \mathcal{D}$
- ② We have a candidate solution  $\mathbf{x}_1$  in mind
- ③ Is it worth developing a stochastic model:  $\mathcal{D} \rightarrow F$ ?
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The Value of Stochastic Modelling ( $\mathcal{VSM}$ ) gives an optimistic estimate of the value of obtaining perfect information about  $F$ .

$$\mathcal{VSM}(\mathbf{x}_1) := \sup_{F \in \mathcal{D}} \left\{ \max_{\mathbf{x}_2} \mathbb{E}_F[h(\mathbf{x}_2, \xi)] - \mathbb{E}_F[h(\mathbf{x}_1, \xi)] \right\}$$

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## Theorem

*Unfortunately, evaluating  $\mathcal{VSM}(\mathbf{x}_1)$  exactly is NP-hard in general.*

# Bounding the Value of Stochastic Modelling

## Theorem

If  $S \subseteq \{\xi \mid \|\xi\|_1 \leq \rho\}$ , an upper bound can be evaluated in  $O(d^{3.5} + d T_{DCP})$  using:

$$\begin{aligned} \mathcal{UB}(\mathbf{x}_1, \bar{\mathbf{y}}_1) &:= \min_{s, \mathbf{q}} && s + \boldsymbol{\mu}^\top \mathbf{q} \\ \text{s.t.} &&& s \geq \alpha(\rho \mathbf{e}_i) - \rho \mathbf{e}_i^\top \mathbf{q}, \forall i \in \{1, \dots, d\} \\ &&& s \geq \alpha(-\rho \mathbf{e}_i) + \rho \mathbf{e}_i^\top \mathbf{q}, \forall i \in \{1, \dots, d\}, \end{aligned}$$

where  $\alpha(\xi) = \max_{\mathbf{x}_2} h(\mathbf{x}_2, \xi) - h(\mathbf{x}_1, \xi; \bar{\mathbf{y}}_1)$ .

# Are Airlines Adventurous in their Fleet Acquisition?

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  - Fleet contracts are signed 10 to 20 years ahead of schedule.
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- Yet, most airline companies sign these contracts based on a single scenario of what the future may be.
- Are airlines companies being neglectful?

# Mathematical formulation for Fleet Mix Problem

The fleet composition problem is a stochastic mixed integer LP

$$\text{Fleet mix} \xrightarrow{\mathbf{x}} \max. \quad \mathbb{E} \left[ - \underbrace{\mathbf{o}^T \mathbf{x}}_{\text{ownership cost}} + \underbrace{h(\mathbf{x}, \tilde{\mathbf{p}}, \tilde{\mathbf{c}}, \tilde{\mathbf{L}})}_{\text{future profits}} \right],$$



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with  $h(\mathbf{x}, \tilde{\mathbf{p}}, \tilde{\mathbf{c}}, \tilde{\mathbf{L}}) :=$

$$\begin{aligned} \max_{z \geq 0, y \geq 0, w} \quad & \sum_k \left( \underbrace{\sum_i \tilde{p}_i^k w_i^k}_{\text{flight profit}} - \underbrace{\tilde{c}_k (z_k - x_k)^+}_{\text{rental cost}} + \underbrace{\tilde{L}_k (x_k - z_k)^+}_{\text{lease revenue}} \right) \\ \text{s.t.} \quad & w_i^k \in \{0, 1\}, \forall k, \forall i \quad \& \quad \sum_k w_i^k = 1, \forall i \quad \left. \vphantom{\sum_k} \right\} \text{Cover} \\ & y_{g \in \text{in}(v)}^k + \sum_{i \in \text{arr}(v)} w_i^k = y_{g \in \text{out}(v)}^k + \sum_{i \in \text{dep}(v)} w_i^k, \forall k, \forall v \quad \left. \vphantom{\sum_k} \right\} \text{Balance} \\ & z_k = \sum_{v \in \{v | \text{time}(v)=0\}} (y_{g \in \text{in}(v)}^k + \sum_{i \in \text{arr}(v)} w_i^k), \forall k \quad \left. \vphantom{\sum_k} \right\} \text{Count} \end{aligned}$$

# Experiments in Fleet Mix Optimization

We experimented with three test cases :

- ❶ 3 types of aircraft, 84 flights,  $\sigma_{\tilde{p}_i} / \mu_{\tilde{p}_i} \in [4\%, 53\%]$
- ❷ 4 types of aircraft, 240 flights,  $\sigma_{\tilde{p}_i} / \mu_{\tilde{p}_i} \in [2\%, 20\%]$
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Results:

Test cases	CPU Time		DRO sub-optimality	
	DRO	SP with $\hat{F}$	Under $\hat{F}$	$\forall F \in \mathcal{D}$
#1	0.6 s	3 min	0.001%	< 6%
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Conclusions:

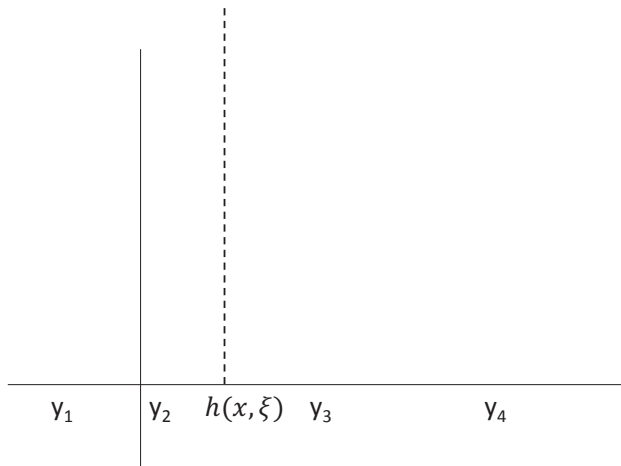
- It's wasteful to invest more than 7% of profits in extra info

# Outline

- 5 Distributionally Robust Partitioning
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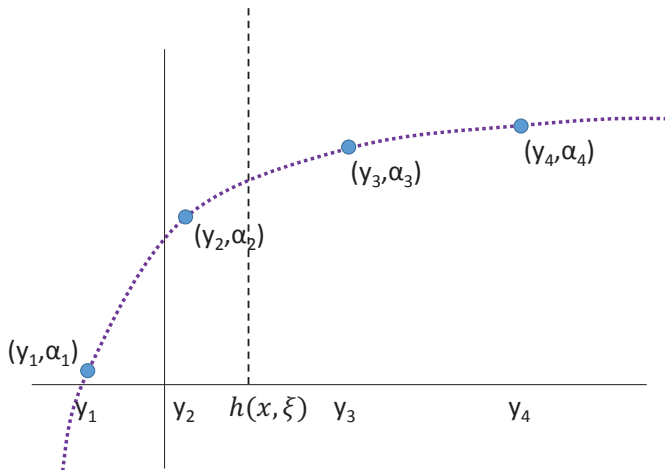
# Constructing the Worst-case Utility I

- Define  $\mathcal{S} = \{y_1, y_2, \dots, y_N\}$  contains support of  $\mathcal{W}_k$  and  $\mathcal{Y}_k$ , and  $t$ .
- Define the values  $\alpha_i := u(y_i)$



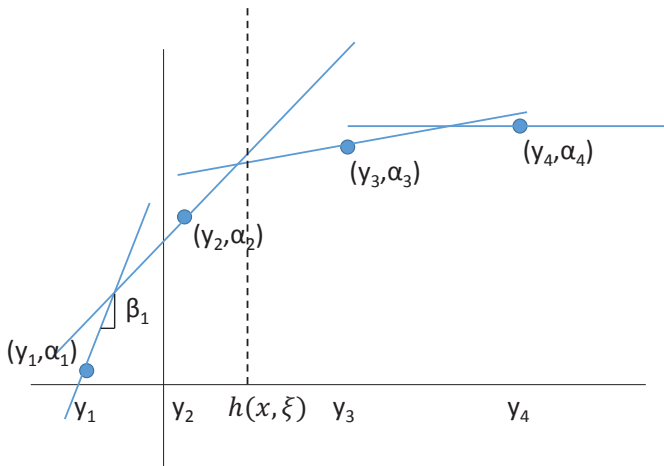
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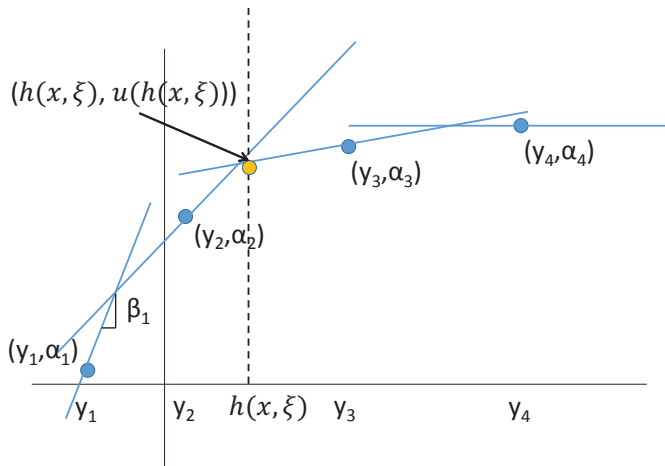
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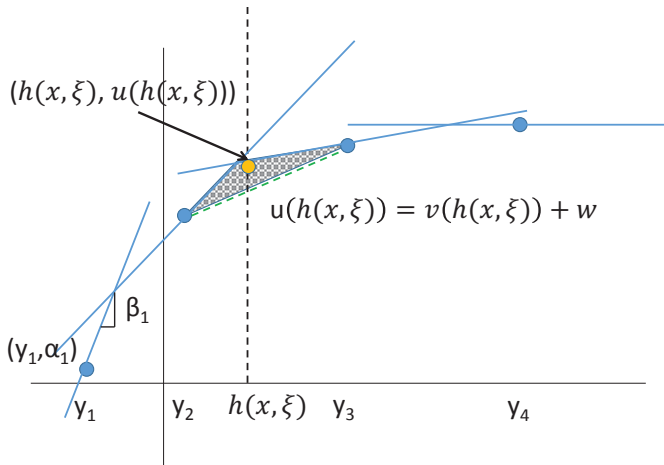
# Constructing the Worst-case Utility II

- Once all  $(y_i, u(y_i))$  are fixed, identify the worst-case utility value for  $u(h(x, \xi))$ .



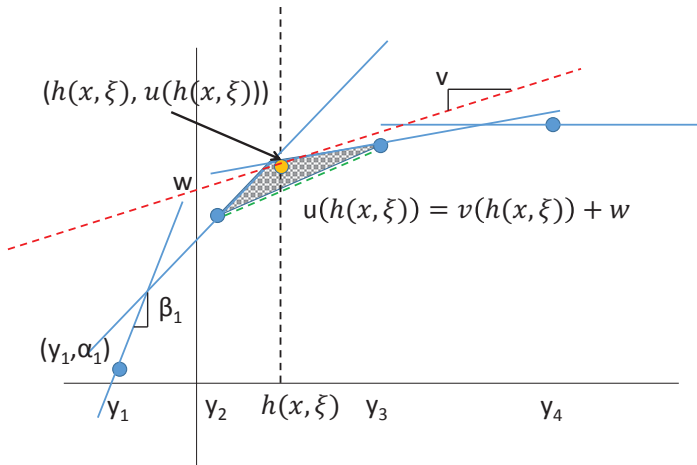
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# LP reformulation of $\inf_{u \in \mathcal{U}} E[u(h(\mathbf{x}, \xi))] - u(t)$

We wish to find an  $\mathbf{x}$  s.t. the following finite dimensional LP has a positive optimal value:

$$\begin{aligned}
 \min_{\alpha, \beta, v, w} \quad & \sum_i p_i (v_i h(\mathbf{x}, \xi^i) + w_i) - \alpha_t \\
 \text{s.t.} \quad & v_i y_i + w_i \geq \alpha_j \quad \forall i, j \quad (\text{Risk aversion at } h(\mathbf{x}, \xi^i)) \\
 & \sum_j P(\mathcal{W}_k = y_j) \alpha_j \geq \sum_j P(\mathcal{Y}_k = y_j) \alpha_j \quad \forall k \quad (\text{Local pref's}) \\
 & \alpha_{j+1} \leq \alpha_j + \beta_j (y_{j+1} - y_j) \quad \forall j \quad (\text{Risk aversion at } y_j \text{'s}) \\
 & \alpha_{j-1} \leq \alpha_j + \beta_j (y_{j-1} - y_j) \quad \forall j \\
 & v \geq 0, \beta \geq 0 \quad (\text{Monotonicity})
 \end{aligned}$$

After taking the dual of this LP, we can join the maximization with  $\mathbf{x} \in \mathcal{X}$

► Back to talk