(Data-Driven) Conditional Robust Optimization

Abhilash Chenreddy Erick Delage

HEC Montréal & GERAD Montréal, Canada

Seminar in honour of Yinyu's career achievements Stanford University July 29th, 2024

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Chaires de recherche du Canada

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Portfolio optimization with contextual information

Problem: How to invest wealth among a set of assets?

$$
x^*(\psi):=\text{arg}\underset{x:\sum_{i=1}^n x_i=1,\ x\geq 0}{\text{min}}\text{VaR}_{1-\epsilon}(\xi^\intercal x|\psi)
$$

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What is contextual stochastic optimization?

- Optimization problems arising in practice almost always involve $\mathsf{unknown}\ \mathsf{parameters}\ \xi \in \mathbb{R}^{m_\xi}$
- Oftentimes, there is a relationship between unknown parameters and some $\textbf{contextual data} \ \psi \in \mathbb{R}^{m_\psi}$

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What is contextual stochastic optimization?

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• **Contextual Optimization**:

- Optimizes a policy, $\mathbf{x} : \mathbb{R}^{m_{\psi}} \to \mathcal{X}$
	- I.e., action $x \in \mathcal{X}$ is adapted to the observed context ψ
- **Contextual Stochastic Optimization** problem minimizes the expected cost of running the policy over the joint distribution of (ψ, ξ) :

$$
\min_{\mathbf{x}(\cdot)} \mathbb{E}[c(\mathbf{x}(\psi), \xi)] \Leftrightarrow \mathbf{x}^*(\psi) \in \argmin_{\mathbf{x} \in \mathcal{X}} \mathbb{E}[c(\mathbf{x}, \xi)|\psi] \text{ a.s.}
$$

What is conditional robust optimization?

• We introduce a **Conditional Robust Optimization** model for solving contextual optimization problems in a risk-averse setting:

$$
\text{(CRO)} \qquad \mathbf{x}^*(\psi) \in \underset{\mathbf{x} \in \mathcal{X}}{\text{arg min}} \underset{\xi \in \mathcal{U}(\psi)}{\text{max}} c(\mathbf{x}, \xi), \,\forall \, \psi \in \mathcal{V}
$$

where $\mathcal{U}(\psi)$ is a **conditional uncertainty set** designed to contain with high probability the realization of ζ conditionally on observing ψ .

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Estimate-then-Optimize with continuous adaptation

• We consider a continuously adapted conditional ellipsoidal set:

 $\mathcal{U}_{\theta}(\psi):=\{~\xi\in\mathbb{R}^{\textit{m}}\epsilon:(\xi-\mu_{\theta}(\psi))^\textit{T}\Sigma^{-1}_{\theta}~\}$ $\bar{\theta}^{-1}(\psi)(\xi-\mu_{\theta}(\psi))\leq R_{\theta}\},$

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Estimate-then-Optimize with continuous adaptation

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$$
\mathcal{U}_{\theta}(\psi) := \{ \xi \in \mathbb{R}^{m_{\xi}} : (\xi - \mu_{\theta}(\psi))^T \Sigma_{\theta}^{-1}(\psi)(\xi - \mu_{\theta}(\psi)) \le R_{\theta} \},
$$

• Given a data set $\mathcal{D} = \{(\psi_1, \xi_1), (\psi_2, \xi_2) \dots (\psi_N, \xi_N)\}\,$ an estimate-then-optimize (ETO) approach takes the form:

$$
\underbrace{\mathcal{D}}_{\text{min}_\theta \mathcal{L}_{\text{NLL}}^{\xi|\psi}(\textit{f}_{\theta}(\cdot),\mathcal{D})} \underbrace{\mathcal{U}_{\theta^{*}}(\cdot)}_{\text{max}_{\xi \in \mathcal{U}_{\theta^{*}}(\psi)} \textit{c(x, \xi)}} \underbrace{\mathcal{X}^{*}(\cdot)}_{\text{max}_{\xi \in \mathcal{U}_{\theta^{*}}(\psi)} \textit{c(x, \xi)}}
$$

where $\mathcal{L}^{\xi|\psi}_{\mathsf{NLL}}$ is the negative log likelihood for a conditional Gaussian density estimator (see [Barratt and Boyd \[2021\]](#page-37-0)):

$$
\xi \sim f_{\theta}(\psi) := \mathcal{N}(\mu_{\theta}(\psi), \Sigma_{\theta}(\psi))
$$

and R_{θ} s.t. $\mathbb{P}_{\mathcal{D}}(\xi \in \mathcal{U}_{\theta}(\psi)) = 1 - \epsilon$

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Related work in operations research literature

- Data-driven Distributionally Robust Optimization:
	- Moment-based DRO: $D & Ye$ (> 2000 citations !!!), etc.
	- Divergence-based DRO: [Ben-Tal et al. \[2013\]](#page-37-1), [Duchi et al. \[2021\]](#page-38-1), etc.
	- Wassertein-based DRO: [Mohajerin Esfahani and Kuhn \[2018\]](#page-39-0), [Gao and](#page-38-2) [Kleywegt \[2023\]](#page-38-2), etc.
- Contextual Stochastic Optimization:
	- [Hannah et al. \[2010\]](#page-39-1), [Bertsimas and Kallus \[2020\]](#page-37-2), …: Conditional distribution estimation used to formulate and solve the CSO problem.
	- [Donti et al. \[2017\]](#page-38-3), [Elmachtoub and Grigas \[2022\]](#page-38-4), …: End-to-end paradigm applied to solve the data driven CSO problem.
- Distributionally Robust CSO:
	- [Bertsimas et al. \[2022\]](#page-37-3), [McCord \[2019\]](#page-39-2), [Wang and Jacquillat \[2020\]](#page-40-0), [Kannan et al. \[2020\]](#page-39-3): DRO approaches with ambiguity sets centered at the estimated conditional distribution
	- [Nguyen et al. \[2021\]](#page-39-4)[,Esteban-Pérez and Morales \[2022\]](#page-38-5): Wasserstein DRO for non-parametric CSO

Related work in data-driven robust optimization literature

- Estimate then RO:
	- [Goerigk and Kurtz \[2023\]](#page-38-6), [Johnstone and Cox \[2021\]](#page-39-5): learns non-contextual uncertainty sets using deep learning, and conformal prediction.
	- [Chenreddy et al. \[2022\]](#page-37-4) learns a contextual uncertainty set using an integrated clustering then classification approach, [Blanquero et al.](#page-37-5) [\[2023\]](#page-37-5) constructs contextual ellipsoidal sets by making normality assumptions
	- [Sun et al. \[2024\]](#page-39-6) solves a robust contextual LP problem by calibrating a predictive model to match robust objectives
	- [Ohmori \[2021\]](#page-39-7), [Sun et al. \[2023\]](#page-39-8): calibrates a box/ellipsoidal set to cover the realizations of a kNN/residual-based conditional distribution.
- End-to-end RO
	- [Wang et al. \[2023\]](#page-40-1) learns non-contextual sets to maximize performance across a set of randomly drawn parameterized robust constrained problems while ensuring constraint satisfaction guarantees w.r.t the joint distribution over perturbance and robust problems
	- [Costa and Iyengar \[2023\]](#page-38-7): proposes a distributionally robust end-to-end system that integrates point prediction and robustness tuning to the E ▶ ④ 토 ▶ 토 트 - 9 Q Q portfolio construction problem

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Our contributions

- Limitation of existing CRO approaches:
	- **1** Training disregards entirely the out-of-sample performance of the solution obtained from robust optimization.

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Our contributions

- Limitation of existing CRO approaches:
	- **1** Training disregards entirely the out-of-sample performance of the solution obtained from robust optimization.
	- 2 While the calibration process encourages **marginal coverage**:

$$
\mathbb{P}(\xi \in \mathcal{U}(\psi)) \ge 1 - \epsilon \blacktriangleright
$$

it does not promote **conditional coverage** over all ψ:

$$
\mathbb{P}(\xi \in \mathcal{U}(\psi)|\psi) \ge 1 - \epsilon \text{ a.s.}
$$

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Desirable coverage properties for $\mathcal{U}(\psi)$ $\boldsymbol{\nu}$ states the properties for $\boldsymbol{\nu}(\psi)$ T_{loc} the time in both groups. The interaction for $1/(q_0)$ $\boldsymbol{\nu}$ states the properties for $\boldsymbol{\nu}(\psi)$ T_{loc} the time in both groups. The interaction for $1/(q_0)$ $\boldsymbol{\nu}$ states the properties for $\boldsymbol{\nu}(\psi)$

The field of conformal prediction identifies two important properties for conditional uncertainty sets

- Marginal coverage property: $\mathbb{P}(\xi \in \mathcal{U}(\psi)) \geq 1 \epsilon$
- Conditional coverage property: $\mathbb{P}(\xi \in \mathcal{U}(\psi)|\psi) \geq 1 \epsilon$ a.s.

Image from Angelopoulos and Bates, A Gentle Introduction to Conformal Prediction and Distribution-Free Uncertainty Quantification, CoRR, 2021. **Image from Angelopoulos and Bates, A Gentle Introduction to Conformal Prediction and Distribution-Free Uncertainty Quantification, CoRR, 2021.**
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(Single) Task-based Set (TbS) training

A task-based approach learns the estimator by trying to minimize the decision loss, e.g. the portfolio risk based on VaR

Decision loss relaxation and derivatives

 $\bullet\,$ Decision loss $\mathsf{VaR}_\mathcal{D}(c(x^*_\theta(\psi),\xi))$ suffers from multiple local optima.

Figure 3: Simulation-based trade risk profile

Image from Mausser and Rosen, Beyond VaR: from measuring risk to managing risk, CIFEr, 1999.

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Figure 3: Simulation-based trade risk profile

Image from Mausser and Rosen, Beyond VaR: from measuring risk to managing risk, CIFEr, 1999.

• We therefore replace it with upper bound $\mathsf{CVaR}_\mathcal{D}(c(x^*_\theta(\psi), \xi)).$

$$
\frac{\partial \text{CVaR}_{i\sim N}(y_i)}{\partial y_i} = v_i(y) \text{ with } \mathbf{v}(\mathbf{y}) \in \operatorname*{argmax}_{\mathbf{v} \in \mathbb{R}_+^M : \mathbf{v}^T \mathbf{v} = 1, \mathbf{v} \leq ((1-\alpha)N)^{-1}} \mathbf{v}^T \mathbf{y}
$$

Decision loss relaxation and derivatives

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• We assume that $c(x, \xi)$ is convex in x and concave in ξ , while X is a convex set.

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- We assume that $c(x, \xi)$ is convex in x and concave in ξ , while X is a convex set.
- Using Fenchel duality, one can follow [Ben-Tal et al. \[2015\]](#page-37-8) to reformulate the robust optimization problem as:

$$
x_{\theta}^{*}(\psi) := \arg\min_{x \in \mathcal{X}} \max_{\xi \in \mathcal{U}_{\theta}(\psi)} c(x, \xi) = \arg\min_{v, x \in \mathcal{X}} \underbrace{\delta^{*}(v|\mathcal{U}_{\theta}(\psi)) - c_{*}(x, v)}_{f(x, v, \mathcal{U}_{\theta}(\psi))}
$$

where the support function

$$
\delta^*(v|\mathcal{U}_{\theta}(\psi)) := \sup_{\xi \in \mathcal{U}_{\theta}(\psi)} \xi^T v = \mu^T v + \sqrt{v^T \Sigma v}
$$

while the partial concave conjugate function is defined as

$$
c_*(x,v) := \inf_{\xi} v^T \xi - c(x,\xi)
$$

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$$

• The derivatives of $x^*_{\theta}(\psi) := \arg\min_{v,x \in \mathcal{X}} f(x,v,\mathcal{U}_{\theta}(\psi))$ w.r.t. θ can be obtained using implicit differentiation (see [Blondel et al. \[2022\]](#page-37-9))

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- $\bullet \, \, (\psi, \xi) \in \mathbb{R}^2 \times \mathbb{R}^2$ drawn from a joint Gaussian mixture model with two modes
- Data: 600 points for training, 400 for validation, 1000 for test
- Targeted confidence level of 90%
- Average is calculated over 10 runs

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Second-task: Conditional coverage

Lemma

An uncertainty set $U_{\theta}(\psi)$ has an a.s. conditional coverage of $1 - \epsilon$ if and only if

 $\mathcal{L}_{\text{CC}}(\theta) := \mathbb{E} [\left(\mathbb{P}(\xi \in \mathcal{U}_{\theta}(\psi) | \psi) - (1 - \epsilon) \right)^2] = 0$

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 $\mathcal{L}_{\text{CC}}(\theta)$ can be approximated using:

$$
\widehat{\mathcal{L}}_{\mathsf{CC}}(\theta) := \mathbb{E}_{\mathcal{D}}[(g_{\phi^*(\theta)}(\psi) - (1 - \epsilon))^2]
$$

where $g_{\phi^*(\theta)}(\psi) \approx \mathbb{P}(\xi \in \mathcal{U}_{\theta}(\psi)|\psi)$ is obtained using logistic regression of membership variable $v(\psi, \xi; \theta) := \mathbb{1}\{\xi \in \mathcal{U}_{\theta}(\psi)\}\$ on ψ .

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• I.e., letting the augmented data set

$$
\mathcal{D}_{\psi\xi y}^{\theta} := \{(\psi_1,\xi_1,y(\psi_1,\xi_1;\theta)),\ldots,(\psi_N,\xi_N,y(\psi_N,\xi_N;\theta))\},\,
$$

one solves $\phi^*(\theta)\in \mathsf{argmin}_\phi \, \mathcal{L}_{NLL}^{\mathsf{y}|\psi}(\mathcal{g}_\phi(\cdot), \mathcal{D}^{\theta}_{\psi \xi \mathsf{y}})$ with

$$
g_{\phi}(\psi) := \frac{1}{1 + \exp^{\phi^T \psi + \phi_0}}
$$

Double Task-based Set (DTbS) training

We train $\mathcal{U}_{\theta}(\psi)$ using the two tasks: produce good decision $+$ produce good conditional coverage:

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(See uncertainty set animation [\(url\)](http://tintin.hec.ca/pages/erick.delage/videoCRO.mp4))

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Portfolio optimization with market data

- Contextual info: Trading volume, volatility index (VIX), 10-year treasury yield index (TNX), oil index (CLF), S&P 500 (GSPC), gold price (GC=F), Dow Jones (DJI).
- Market data from Yahoo! Finance: 70 different stocks during period from 01/01/2012 to 31/12/2019 (2017-2019 reserved for test).
- Target confidence level of 70%, 80%, or 90%

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Concluding remarks

- We introduced a new conditional robust optimization approach for solving risk averse contextual optimization problems.
- In CRO, deep neural networks can be used to:
	- Represent richly structured uncertainty sets (see [Goerigk and Kurtz](#page-38-6) [\[2023\]](#page-38-6), [Chenreddy et al. \[2022\]](#page-37-4))
	- Adapt uncertainty set continuously to covariates (this talk)
- Two types of training objectives:
	- Decision performance: Producing decisions that achieve low VaR/CVaR
	- Statistical performance: achieving the right marginal/conditional coverage

Thank you Professor Ye for your mentoring, guidance, and support throughout all these years.

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